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Higher order methods-IV

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[6-C-04] Locally Divergence-Free Oscillation-Eliminating Discontinuous Galerkin Methods for Ideal MHD Equations

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Locally Divergence-Free Oscillation-Eliminating Discontinuous Galerkin Methods for Ideal MHD Equations

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1 Abstract

The ideal magnetohydrodynamics (MHD) equations describe the dynamic behaviors of a perfectly conducting quasi-neutral plasma. Numerical simulation of ideal compressible MHD is challenging, as it needs to be magnetic divergence-free for general cases as well as oscillation-free for cases involving discontinuities. To overcome these difficulties, we propose a locally divergence-free oscillation-eliminating discontinuous Galerkin (LDF-OEDG) method. A set of enriched polynomial basis functions that can automatically satisfy the local divergence-free property [1] are used to approximate the solution on each control volume. The piece-wise LDF polynomials are limited in an oscillation-eliminating (OE) procedure [2] to suppress spurious oscillations near discontinuities. The solutions are updated by using the strong stability preserving Runge-Kutta time integration schemes [3]. The method has the following characteristics: (i) magnetic divergence-free; (ii) stable under normal CFL conditions; (iii) free of characteristic decomposition; (iv) non-intrusive, simple and efficient. The implementation of the LDF-OEDG scheme is described in Algorithm 1. The robustness and accuracy of the proposed method are validated by several benchmark MHD cases, including the vortex problem [4] (see Table 1), the Orszag-Tang problem [5] (see Figure 1), Rotor problem [6] (see Figure 2), etc.

Algorithm 1 LDF-OEDG for ideal compressible MHD equations.

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1: function  $\mathbf{U}_\sigma^{n+1} = \text{LDF-OEDG}(\mathbf{U}_\sigma^n, \tau)$ 
2:   Set  $\mathbf{U}_\sigma^{n,0} = \mathbf{U}_\sigma^n$ 
3:   Set SSPRK3 coefficients:  $c_1 = 1, c_2 = \frac{1}{4}, c_3 = \frac{2}{3}$ 
4:   for  $s \leftarrow 1, 3$  do
5:     Surface and volume flux integrals in (1) to compute right-hand-side  $\mathcal{T}_f(\mathbf{U}_\sigma^{n,s-1})$ 
6:     Runge-Kutta stage update  $\mathbf{U}_h^{n,s} = (1 - c_s) \mathbf{U}_\sigma^n + c_s (\mathbf{U}_\sigma^{n,s-1} + \tau \mathcal{T}_f(\mathbf{U}_\sigma^{n,s-1}))$ 
7:     OE procedure  $\mathbf{U}_\sigma^{n,s} = \mathcal{F}_\tau \mathbf{U}_h^{n,s}$  using the exact damping operator in (2)
8:     Splitting of  $\mathbf{U}_\sigma^{n,s}$  into two parts: the flow field  $\mathbf{U}_{\sigma,F}^{n,s}$  and the magnetic field  $\mathbf{B}_\sigma^{n,s,*}$ 
9:     Projection of  $\mathbf{B}_\sigma^{n,s,*}$  to obtain a LDF magnetic field  $\mathbf{B}_\sigma^{n,s}$ , as in (3)
10:    Formation of a divergence- and oscillation-free solution  $\mathbf{U}_\sigma^{n,s} = (\mathbf{U}_{\sigma,F}^{n,s}, \mathbf{B}_\sigma^{n,s})^T$ 
11:  end for
12:  Update solution  $\mathbf{U}_\sigma^{n+1} = \mathbf{U}_\sigma^{n,3}$ 
13: end function

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Here,

$$\int_K (\mathbf{U}_h)_t \phi_K^{(\alpha)} d\mathbf{x} + \oint_{\partial K} \hat{\mathbf{F}} \cdot \mathbf{n} \phi_K^{(\alpha)} ds - \int_K \mathbf{F} \cdot \nabla \phi_K^{(\alpha)} d\mathbf{x} = 0, \quad |\alpha| \leq k, \quad (1)$$

$$\mathcal{F}_\tau \mathbf{U}_h = \mathbf{U}_K^{(0)} \phi_K^{(0)}(\mathbf{x}) + \sum_{j=1}^k e^{-\tau \sum_{m=0}^j \delta_K^m(\mathbf{U}_h)} \sum_{|\alpha|=j} \mathbf{U}_K^{(\alpha)} \phi_K^{(\alpha)}(\mathbf{x}), \quad (2)$$

$$\mathbf{B}_h^{n+1} = \sum_{l=1}^9 B_K^{(l)} \psi_K^{(l)}, \quad B_K^{(l)} = \frac{\int_K \mathbf{B}_h^{n+1,*} \cdot \psi_K^{(l)} d\mathbf{x}}{\int_K \psi_K^{(l)} \cdot \psi_K^{(l)} d\mathbf{x}}. \quad (3)$$

Table 1: Accuracy test results for the vortex problem.

Mesh	ρ		ρu_x		B_x		E	
	L^2 -error	Order	L^2 -error	Order	L^2 -error	Order	L^2 -error	Order
16×16	2.12E-03		1.10E-02		1.14E-02		1.50E-02	
32×32	2.59E-04	3.03	5.92E-04	4.22	5.84E-04	4.28	9.88E-04	3.93
64×64	4.45E-05	2.54	5.54E-05	3.42	5.17E-05	3.50	1.23E-04	3.01
128×128	7.29E-06	2.61	7.83E-06	2.82	6.51E-06	2.99	1.86E-05	2.73

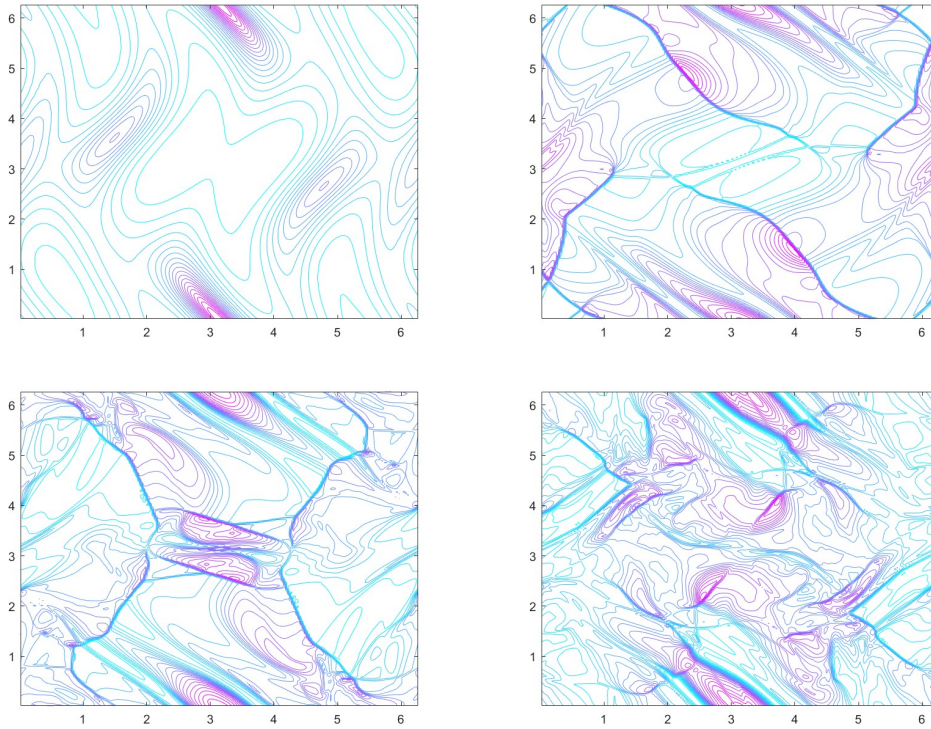


Figure 1: Orszag-Tang problem. Density contours at $t = 0.5$ (top left), $t = 2$ (top right), $t = 3$ (bottom left) and $t = 4$ (bottom right), respectively, computed by LDF-OEDG on a 192×192 mesh.

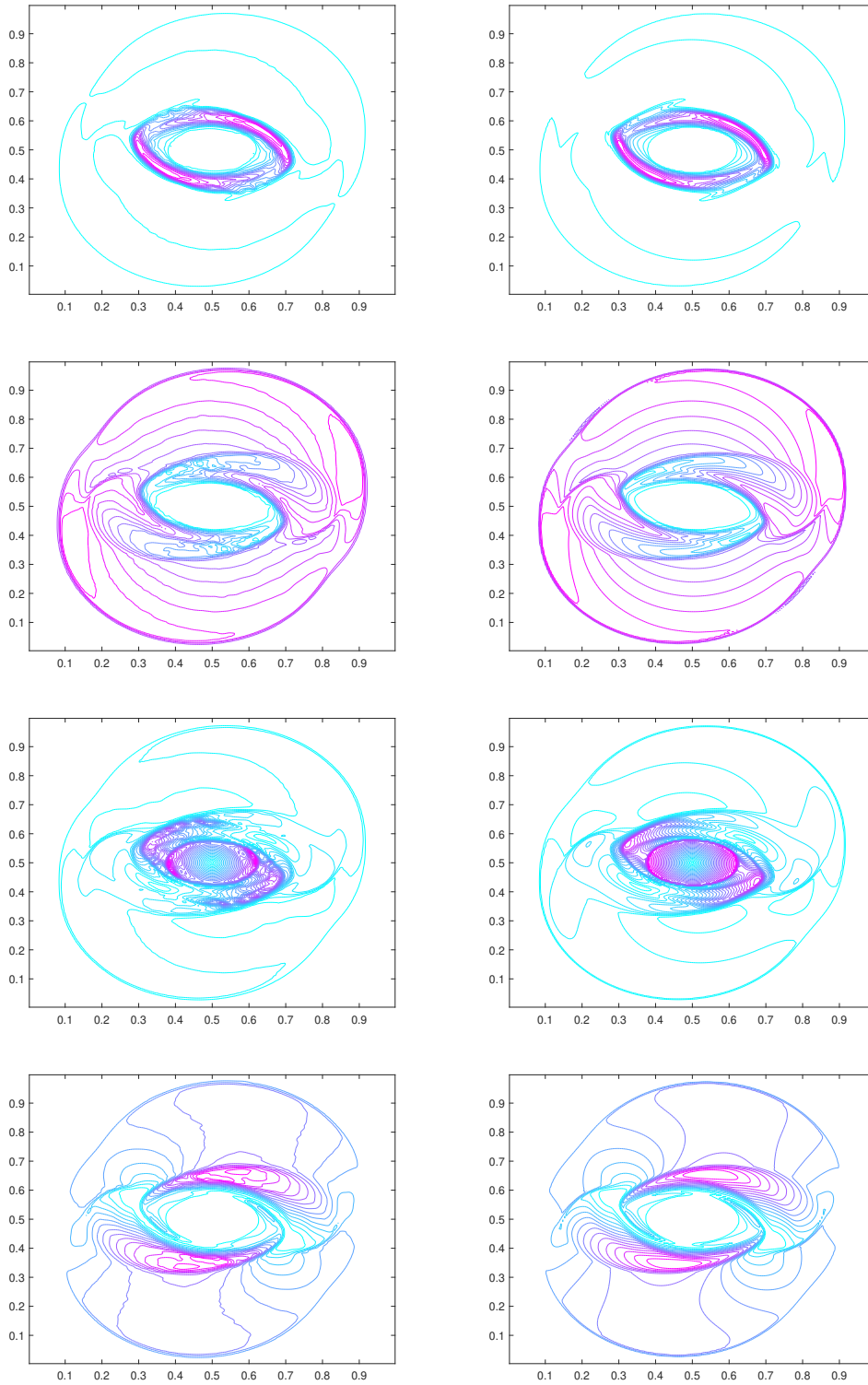


Figure 2: Rotor problem. From top to bottom: contour plots of the density ρ , thermal pressure p , Mach number $\|\mathbf{u}\|_2/c$ and magnetic pressure $\|\mathbf{B}\|_2^2/2$, respectively. The solutions are computed on a 200×200 mesh. Left: LDF-DG with TVB limiter; right: LDF-OEDG.

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